

# Existence of solutions and other properties for an internal wave model

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# The Nonlinear ILW System

We consider the nonlinear ILW system

$$\begin{aligned}\eta_t &= [(1 - \alpha\eta)u]_x \\ u_t &= \eta_x - \alpha uu_x\end{aligned}$$

with initial data

$$\eta(x, 0) = \eta_0(x), \quad u(x, 0) = u_0(x).$$

$t$  denote the time variable and the spatial variable  $x$  stands in

$$\mathbb{R} \quad \text{or} \quad \mathbb{T} = [-\pi, \pi] \text{ (periodic functions).}$$

## Questions

- 1 Existence of local solutions?
- 2 Blow up? or Global solutions?
- 3 Other properties?

## A Friendly System

A system with more properties is given by

$$\begin{aligned}\eta_t &= [(1 - \alpha\eta)u]_x \\ u_t &= \eta_x - \alpha uu_x + M(u) + N(u)\end{aligned}$$

where  $M(u)$  denote dispersive terms and  $N(u)$  denote dissipative terms.

- Some dispersive terms are

$$u_{xxt}, \quad H(u_{xt}), \quad \mathcal{T}(u_{xt}), \quad u_{xxx}, \quad \text{etc.}$$

- Some dissipative terms are

$$\delta u_{xx}, \quad H(u_x), \quad \mathcal{T}(u_x), \quad -u_{xxxx}, \quad \text{etc.}$$

## Our problem

We will study the following nonlinear system

$$\begin{aligned}\eta_t &= [(1 - \alpha\eta)u]_x \\ u_t &= \eta_x - \alpha uu_x + \delta u_{xx}\end{aligned}$$

with initial data

$$\eta(x, 0) = \eta_0(x), \quad u(x, 0) = u_0(x).$$

where the spatial variable stands at

$$x \in \mathbb{T} = [-\pi, \pi] \quad (\text{periodic solutions}).$$

## Questions

- 1 Existence of local solutions?
- 2 Blow up? or Global solutions?
- 3 Smoothing properties?
- 4 Asymptotic behavior?
- 5 Who is the limit?
- 6 Speed of this asymptotic behavior?

The nonlinear system can be written in the abstract framework

$$\frac{d}{dt} U = \mathbb{A}_0 U + \mathbb{A} \mathbb{F}(U),$$

where

$$U = \begin{pmatrix} \eta \\ u \end{pmatrix}, \quad \mathbb{A} = \begin{bmatrix} \partial_x & 0 \\ 0 & \partial_x \end{bmatrix}, \quad \mathbb{A}_0 = \begin{bmatrix} 0 & \partial_x \\ \partial_x & \delta \partial_{xx} \end{bmatrix},$$

$$\mathbb{F}(U) = \begin{pmatrix} -\alpha \eta u \\ -\alpha u^2/2 \end{pmatrix}.$$

We will work in the space

$$\mathbb{H}^s = H^s(\mathbb{T}) \times H^s(\mathbb{T}), \quad s \geq 0$$

with the the inner product

$$\langle U_1, U_2 \rangle = \langle \eta_1, \eta_2 \rangle_{H^s(\mathbb{T})} + \langle u_1, u_2 \rangle_{H^s(\mathbb{T})}.$$

This operators are defined in

$$D(\mathbb{A}) = \mathbb{H}^{s+1}, \quad D(\mathbb{A}_0) = \{U \in \mathbb{H}^s : \mathbb{A}_0(U) \in \mathbb{H}^s\}$$

and

$$D(\mathbb{F}) = \mathbb{H}^s \quad (\text{for } s > 1/2).$$



Note that  $D(\mathbb{A}_0)$  is characterized by

$$D(\mathbb{A}_0) = \{U \in \mathbb{H}^s : u \in H^{s+1}(\mathbb{T}), \eta + \delta u_x \in H^{s+1}(\mathbb{T})\}.$$

is easy to see that

$$H^{s+1}(\mathbb{T}) \times H^{s+2}(\mathbb{T}) \subset D(\mathbb{A}_0) \subset \mathbb{H}^s.$$

Therefore  $A_0$  is densely defined.

Some properties of the linearized system are preserved by the nonlinear system. In this case the linearized system is

$$\begin{aligned}\eta_t &= u_x, \\ u_t &= \eta_x + \delta u_{xx}.\end{aligned}$$

This system can be written in the abstract framework by

$$\frac{d}{dt}U = \mathbb{A}_0 U.$$

## Theorem

$\mathbb{A}_0$  is the generator of a contractions semigroup.

We use the following result:

## Theorem (Lumer-Phillips)

Let  $\mathbb{A}$  be a operator in a Hilbert space  $\mathbb{X}$ . Then,  $\mathbb{A}$  is the generator of a contractions semigroup if and only if it is densely defined and  $m$ -dissipative.

Definition:  $\mathbb{A}$  is  $m$ -dissipative if

$$\operatorname{Re}\langle \mathbb{A}U, U \rangle_{\mathbb{X}} \leq 0 \quad \text{and} \quad \operatorname{Im}(\lambda I - \mathbb{A}) = \mathbb{X}$$

for some  $\lambda > 0$ .

## Proof

We have

$$\operatorname{Re}\langle \mathbb{A}_0 U, U \rangle = -\delta \|u_x\|^2 < 0,$$

then, the operator  $\mathbb{A}_0$  is dissipative. Let  $F \in \mathbb{H}^s$ , solving the equation  $(I - A_0)U = F$  is equivalent to solve  $(I - \widehat{A_0})U = \widehat{F}$ . If  $\mu = \hat{\eta}$ ,  $\omega = \hat{u}$  is equivalent to solve the system

$$\begin{aligned}\mu - ik\omega &= f \\ \omega - ik(\mu + i\delta k\omega) &= g\end{aligned}$$

where  $(f, g) = \widehat{F}$ . The solutions are

$$\mu = \frac{(1 + \delta k^2)f + ikg}{1 + \delta k^2 + k^2}, \quad \omega = \frac{g + ikf}{1 + \delta k^2 + k^2}.$$

after some computations we verify  $U \in D(\mathbb{A}_0)$ .

With the above theorem for each initial data  $U_0 \in D(\mathbb{A}_0)$ , we have a unique global solutions  $U(t) = e^{t\mathbb{A}_0} U_0$  for the linearized system in the space

$$U \in C([0, \infty[, D(\mathbb{A}_0)) \cap C^1([0, \infty[, \mathbb{H}^s).$$

## Theorem

*The semigroup  $\{e^{t\mathbb{A}_0}\}_{t \geq 0}$  is analytic.*

we use the following result:

**Theorem** (a particular case of this theorem is proved in Liu's book)

*Let  $\mathbb{A}$  the generator of a contractions semigroup  $\{e^{t\mathbb{A}}\}_{t \geq 0}$ . If the following conditions*

- 1  $\rho(\mathbb{A}) \supset i\mathbb{R} \setminus \{0\}$  and
- 2  $\|R(i\lambda, \mathbb{A})\| \leq \frac{C}{|\lambda|}$ , for all  $\lambda \in \mathbb{R}$ ,  $\lambda \neq 0$

*are satisfied, then  $\{e^{t\mathbb{A}}\}_{t \geq 0}$  is an analytic semigroup.*

## Proof

We will use the discrete Fourier transform to show this theorem. If  $(\mu, \omega)$  denote the Fourier transform of  $U = (\eta, u)$ . The system  $(i\lambda I - \mathbb{A}_0)U = F$ , for  $\lambda \in \mathbb{R}$  is satisfied if

$$\begin{aligned}i\lambda\mu - ik\omega &= f, \\i\lambda\omega - ik(\mu + i\delta k\omega) &= g.\end{aligned}$$

Solving this equations we have

$$\mu = -\frac{i(\lambda - i\delta k^2)f + ikg}{\lambda^2 - i\delta k^2\lambda + k^2}, \quad \omega = -\frac{i\lambda g + ikf}{\lambda^2 - i\delta k^2\lambda + k^2}.$$

After some computations we have

$$\|U\| \leq \frac{C}{|\lambda|} \|F\|, \quad \lambda \neq 0.$$

From this estimate we conclude that

$$\rho(\mathbb{A}_0) \supset i\mathbb{R} \setminus \{0\} \quad \text{and} \quad \|\lambda(i\lambda I - \mathbb{A}_0)^{-1}\| \leq C$$

## Returning to the nonlinear system

Applying the technique of parameters variations, the solution of the nonlinear system must satisfy the Duhamel's formula

$$U(t) = e^{tA_0} U_0 + \int_0^t e^{(t-s)A_0} \mathbb{A}\mathbb{F}(U(s)) ds$$

If we consider the operator

$$(GU)(t) = e^{tA_0} U_0 + \int_0^t e^{(t-s)A_0} \mathbb{A}\mathbb{F}(U(s)) ds$$

we use some theorem of fixed point to find solutions of the nonlinear system.



Because  $\mathbb{A}\mathbb{A}_0 = \mathbb{A}_0\mathbb{A}$  in  $D(\mathbb{A}_0) \cap D(\mathbb{A})$  we can verify that  $\mathbb{A}$  commute with  $e^{(t-s)\mathbb{A}_0}$  em  $D(\mathbb{A})$ , and in this case

$$\begin{aligned}(GU)(t) &= e^{t\mathbb{A}_0} U_0 + \int_0^t \mathbb{A} e^{(t-s)\mathbb{A}_0} \mathbb{F}(U(s)) ds \\ &= e^{s\mathbb{A}_0} U_0 + \int_0^t \mathbb{A} e^{s\mathbb{A}_0} \mathbb{F}(U(t-s)) ds.\end{aligned}$$

Difficulty: unfortunately the operator  $\mathbb{A}e^{t\mathbb{A}_0}$  blow up at  $t = 0$ . I explain: it can be show that the function  $t \rightarrow \mathbb{A}e^{t\mathbb{A}_0}$  are continuous in  $L(\mathbb{H}^s)$  for  $t > 0$ . The blow up is consequence of this fact

$$\mathbb{A}e^{t\mathbb{A}_0} \rightarrow \mathbb{A}, \quad \text{when } t \rightarrow 0^+ \quad \text{and} \quad \mathbb{A} \notin L(\mathbb{H}^s).$$

Therefore we need some kind control on  $\|\mathbb{A}e^{t\mathbb{A}_0}\|$  near to  $t = 0$ .  
It is known that  $\mathbb{A}_0e^{t\mathbb{A}_0}$  is a limited operators for  $t > 0$  and

$$\|\mathbb{A}_0e^{t\mathbb{A}_0}\| \leq \frac{C}{t}, \quad t > 0,$$

Because the operator  $\mathbb{A}$  is more “weak” than  $\mathbb{A}_0$ , it is possible to show the same inequality, that is

$$\|\mathbb{A}e^{t\mathbb{A}_0}\| \leq \frac{C}{t}, \quad t > 0,$$

but this do not help me.

## Theorem

There exist  $\theta \in ]0, 1[$  such that

$$\|\mathbb{A}e^{t\mathbb{A}_0}\| \leq \frac{C}{t^\theta}$$

## Corollary

we have the following estimate

$$\int_0^t \|\mathbb{A}e^{s\mathbb{A}_0}\| ds \leq \frac{C}{1-\theta} t^{1-\theta}, \quad \forall t > 0.$$

## Some estimates for the nonlinear term

$$\mathbb{F}(U) = \begin{pmatrix} -\alpha\eta u \\ -\alpha u^2/2 \end{pmatrix} \Rightarrow D\mathbb{F}(U) = \begin{bmatrix} -\alpha u & -\alpha\eta \\ 0 & -\alpha u \end{bmatrix}$$

Therefore  $\|D\mathbb{F}(U)\| \leq C\|U\|$ . Since

$$\mathbb{F}(U_2) - \mathbb{F}(U_1) = \int_0^1 D\mathbb{F}(U_1 + r(U_2 - U_1))(U_2 - U_1) dr,$$

it follows that

$$\|\mathbb{F}(U_2) - \mathbb{F}(U_1)\| \leq C(\|U_1\| + \|U_2\|)\|U_2 - U_1\|.$$

Consequently, if  $\|U_1 - U_0\| \leq R$ ,  $\|U_2 - U_0\| \leq R$  for some  $U_0$ , we have

$$\|\mathbb{F}(U_2) - \mathbb{F}(U_1)\| \leq C(R + \|U_0\|)\|U_2 - U_1\|.$$

## Theorem (Local solutions)

For  $U_0 \in D(\mathbb{A}_0)$ , the nonlinear system has a unique solution in  $C([0, T], \mathbb{H}^s)$  for some  $T > 0$

## Proof

Let  $T > 0$ ,  $R > 0$ , we consider the subset of the space  $C([0, T], \mathbb{H}^s)$ :

$$\mathbb{M}_T = \{U \in C([0, T], \mathbb{H}^s) : U(0) = U_0, U(t) \in \overline{B_R(U_0)}\}.$$

We define the operator  $G : \mathbb{M}_T \rightarrow C([0, T], \mathbb{H}^s)$  given by

$$G(U)(t) = e^{t\mathbb{A}_0} U_0 + \int_0^t \mathbb{A} e^{s\mathbb{A}_0} F(U(t-s)) ds.$$

we have

$$\begin{aligned} & \|G(U)(t) - U_0\| \\ & \leq \|e^{t\mathbb{A}_0} U_0 - U_0\| + \int_0^t \|\mathbb{A} e^{s\mathbb{A}_0}\| (\|F(U(t-s)) - F(U_0)\| + \|F(U_0)\|) ds \\ & \leq \|e^{t\mathbb{A}_0} U_0 - U_0\| + \left( \int_0^t \|\mathbb{A} e^{s\mathbb{A}_0}\| ds \right) \{CR(R + \|U_0\|) + \|F(U_0)\|\} \\ & \leq \|e^{t\mathbb{A}_0} U_0 - U_0\| + C(\theta)t^{1-\theta} \{CR(R + \|U_0\|) + \|F(U_0)\|\}. \end{aligned}$$

Taking  $T$  small we have

$$\|G(U)(t) - U_0\| \leq R, \forall t \in [0, T].$$

This shows that  $G(\mathbb{M}_T) \subset \mathbb{M}_T$  for  $T$  small.

On the other hand,

$$\begin{aligned} & \|G(U_2)(t) - G(U_1)(t)\| \\ & \leq \int_0^t \|\mathbb{A} e^{s\mathbb{A}_0}\| \|F(U_2(t-s)) - F(U_1(t-s))\| ds \\ & \leq \left( \int_0^t \|\mathbb{A} e^{s\mathbb{A}_0}\| ds \right) C(R + \|U_0\|) \|U_2 - U_1\|_{C([0, T], \mathbb{H}^s)} \\ & \leq C(\theta) t^{1-\theta} (R + \|U_0\|) \|U_2 - U_1\|_{C([0, T], \mathbb{H}^s)}. \end{aligned}$$

Taking  $T$  small we have that  $G$  is a contraction operator.

## Questions

- 1 Existence of local solutions? OK
- 2 Blow up? or Global solutions? still trying!
- 3 Smoothing properties? it's possible
- 4 Asymptotic behavior?
- 5 Who is the limit?
- 6 Speed of this asymptotic behavior?



## Asymptotic behavior

If  $(\eta_\infty(x), u_\infty(x))$  is the limit of the solutions  $(\eta(x, t), u(x, t))$  when  $t \rightarrow \infty$ , then  $(\eta_\infty, u_\infty)$  is the solution of the stationary system

$$\begin{aligned} [(1 - \alpha\eta)u]_x &= 0, \\ \eta_x - \alpha u u_x + \delta u_{xx} &= 0. \end{aligned}$$

But the solutions of this this system are constants. Therefore  $\eta_\infty, u_\infty$  are constants. On the other hand, from the preserved amounts

$$\int_{-\pi}^{\pi} \eta(x, t) dx = \int_{-\pi}^{\pi} \eta_0(x) dx, \quad \int_{-\pi}^{\pi} u(x, t) dx = \int_{-\pi}^{\pi} u_0(x) dx$$

we conclude that

$$\eta_\infty = \frac{1}{2\pi} \int_{-\pi}^{\pi} \eta_0(x) dx, \quad u_\infty = \frac{1}{2\pi} \int_{-\pi}^{\pi} u_0(x) dx.$$

If we introduce the notation

$$\tilde{h} = \frac{1}{2\pi} \int_{-\pi}^{\pi} h(x) dx,$$

the space  $H_0^s(\mathbb{T}) = \{h \in H^s(\mathbb{T}) : \tilde{h} = 0\}$  is a closed subspace of  $H^s(\mathbb{T})$ . Consequently, the space

$$\mathbb{H}_0^s = H_0^s(\mathbb{T}) \times H_0^s(\mathbb{T})$$

is a closed subspace of  $\mathbb{H}^s$ . Therefore, it is Hilbert subspace.

Now, note that, if  $(\eta, u) \in \mathbb{H}^s$  is a solution of the nonlinear system if and only if  $(\eta - \tilde{\eta}_0, u - \tilde{u}_0)$  is a solution of the following auxiliary nonlinear system

$$\begin{aligned}\eta_t &= \beta_1 \eta_x + \beta_2 u_x - \alpha(\eta u)_x, \\ u_t &= \beta_3 \eta_x + \beta_4 u_x - \alpha u u_x + \delta u_{xx},\end{aligned}$$

where

$$\beta_1 = \beta_4 = -\alpha \tilde{u}_0, \quad \beta_2 = 1 - \alpha \tilde{\eta}_0, \quad \beta_3 = 1.$$

Moreover, we have

$$(\eta - \tilde{\eta}_0, u - \tilde{u}_0) \in \mathbb{H}_0^s.$$

The auxiliary system can be write as

$$\frac{d}{dt}U = \mathbb{A}_0 U + \mathbb{A}F(U)$$

where

$$\mathbb{A} = \begin{bmatrix} \partial_x & 0 \\ 0 & \partial_x \end{bmatrix}, \quad \mathbb{A}_0 = \begin{bmatrix} \beta_1 \partial_x & \beta_2 \partial_x \\ \beta_3 \partial_x & \beta_4 \partial_x + \delta \partial_{xx} \end{bmatrix}, \quad \mathbb{F}U = \begin{pmatrix} -\alpha \eta u \\ -\alpha u^2/2, \end{pmatrix}$$

with domains

$$D(\mathbb{A}) = \mathbb{H}^{s+1}, \quad D(\mathbb{A}_0) = \{U \in \mathbb{H}^s : \mathbb{A}_0(U) \in \mathbb{H}^s\}$$
$$D(\mathbb{F}) = \mathbb{H}^s \quad (s > 1/2)$$

## Properties of the new operator $\mathbb{A}_0$

- 1  $\mathbb{A}_0$  is a semigroup of contractions  $\{e^{t\mathbb{A}_0}\}_{t \geq 0}$  in the space  $\mathbb{H}^s$  with the appropriate inner product.
- 2 The subspace  $\mathbb{H}_0^s$  is invariant for this semigroup. That is,  $e^{t\mathbb{A}_0}(\mathbb{H}_0^s) \subset \mathbb{H}_0^s$ .
- 3 The semigroup  $\{e^{t\mathbb{A}_0}\}_{t \geq 0}$  is analytic in  $\mathbb{H}^s$ .
- 4 The semigroup  $\{e^{t\mathbb{A}_0}\}_{t \geq 0}$  is analytic and exponentially stable in  $\mathbb{H}_0^s$ . ( $\|e^{t\mathbb{A}_0}\| \leq Me^{-\gamma t}$ ,  $\gamma > 0$ ).
- 5  $\|\mathbb{A}e^{t\mathbb{A}_0}\| \leq \frac{C}{t^\theta}$ , for some  $\theta \in ]0, 1[$

Thus, we have the local solutions for the auxiliary system in  $\mathbb{H}^s$ .

Global solution? **still trying!**

## Theorem

For the solutions of the nonlinear system we have

$$\|\eta - \tilde{\eta}_0\|_{H^s(\mathbb{T})} + \|u - \tilde{u}_0\|_{H^s(\mathbb{T})} \leq Ce^{-\gamma t}.$$

where the constant  $C$  depends of the initial data.

## Proof

We multiply the auxiliary system by  $e^{\gamma t}$ . Thus, the functions  $(e^{\gamma t}\eta, e^{\gamma t}u)$  satisfy the following system

$$\begin{aligned}\eta_t &= (\beta_1 + \gamma)\eta_x + \beta_2 u_x - \alpha e^{-\gamma t}(\eta u)_x, \\ u_t &= \beta_3 \eta_x + (\beta_4 + \gamma)u_x - \alpha e^{-\gamma t}uu_x + \delta u_{xx}.\end{aligned}$$

The operator of the linear part of this system is

$$\mathbb{A}_\gamma = \begin{bmatrix} (\beta_1 + \gamma)\partial_x & \beta_2\partial_x \\ \beta_3\partial_x & (\beta_4 + \gamma)\partial_x + \delta\partial_{xx} \end{bmatrix}.$$

The above system can be written in the abstract framework

$$\frac{d}{dt}U = \mathbb{A}_\gamma U + e^{-\gamma t} \mathbb{A}F(U)$$

$\mathbb{A}_\gamma$  has the same properties to  $\mathbb{A}_0$  for  $\gamma$  small. From Duhamel's formula we have

$$U(t) = e^{t\mathbb{A}_\gamma} U_0 + \int_0^t e^{-\gamma s} e^{(t-s)\mathbb{A}_\gamma} \mathbb{A}F(U(s)) ds.$$

If for the initial data

$$U_0 = \begin{pmatrix} \eta_0 - \tilde{\eta}_0 \\ u_0 - \tilde{u}_0 \end{pmatrix}$$

We will show that this system has global solution and the solution is bounded, that is,  $\|U(t)\| \leq C$ , for all  $t \geq 0$ . This means that

$$\|e^{\gamma t}(\eta - \tilde{\eta}_0)\|_{H^s(\mathbb{T})} + \|e^{\gamma t}(u - \tilde{u}_0)\|_{H^s(\mathbb{T})} \leq C.$$

## References

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